

# Evan Tan

github.com/evantancy | evantancy.github.io | tcyevan@gmail.com

## EDUCATION

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### Monash University

*Bachelor of Robotics and Mechatronics Engineering (Upper Second-Class Honors)*

Melbourne, Australia  
July 2017 - December 2021

- Specialization in Artificial Intelligence
- **Key Achievements:** 2019/2020 - Engineering Leadership Program, 2018 - 1<sup>st</sup> place Australasian FSAE Business Presentation
- **Relevant Coursework:** Machine Learning, Deep Learning, Computer Vision, Robotics

## EXPERIENCE

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### AIDrivers

*Autonomy Engineer*

Singapore  
March 2021 - May 2021

- Co-led the company's first computer vision safety product and oversaw a team for the machine learning pipeline
- Achieved model accuracy over 80% using instance segmentation and computer vision in Python

*Autonomy Engineer Intern*

December 2020 - March 2021

- Successfully automated configuration of development environment using Ansible and Bash scripts
- Improved reliability via containerization of production environment using Docker
- Performed calibration and testing for autonomous sensor suite

## SKILLS

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**Languages:** Solidity, JavaScript, HTML, CSS, Python, C/C++, MATLAB

**Software:** Foundry, Hardhat, Git, Docker, Ansible, Bash, Unix/Linux, ROS, Gazebo, Raspberry Pi

**Libraries:** React, ethers.js, Moralis, PyTorch, NumPy, OpenCV, matplotlib, Jupyter, Shapely

## PROJECTS & RELEVANT COURSEWORK

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### NFT Marketplace

- Created a multi-chain NFT marketplace that detects ERC721 and ERC1155 tokens in a user's wallet to buy and sell tokens
- Programmed a smart contract that handles both ERC721 and ERC1155 tokens for listings and sales

### Random Words NFT

- Programmed ERC721 token contract to randomly generate traits, stored fully on-chain and deployed contract to Rinkeby testnet
- Implemented website using React and ethers.js to allow users to connect wallet and mint tokens
- Tested and deployed contract using foundry

### Deep Reinforcement Learning for Intelligent Traffic Management

September 2021 - October 2021

- Achieved 47% lower waiting time and 10% increased average speed by crafting a novel reward function with expert information for traffic intersections in SUMO-RL
- Managed a team to collaboratively share models and training data using TensorBoard, and enforced version control using Git

### Neural Networks and Deep Learning

July 2021 - November 2021

- Designed custom convolutional neural networks for image classification problems in PyTorch, using additional image transformations to diversify dataset
- Studied occlusion sensitivity on model predictions and visualized the output of convolutional layers

### Computer Vision

March 2021 - May 2021

- Implemented computer vision algorithms such as image convolutions, canny edge detection with non-maxima suppression, K-means clustering, image stitching, and stereo reconstruction in MATLAB

### Teleoperated Pose Estimation Robot

July 2020 - November 2020

- Achieved 100% pose estimation accuracy of detected objects with an average of 0.29m discrepancy with max range of 10m, by combining non-linear regression, bounding box size and intrinsic camera properties
- Led a team for data annotation and labelling for custom objects and trained model on cloud computing resources
- Created scripts to gather annotation datasets for the machine learning pipeline using for ROS and Gazebo simulator in Python
- Optimized program runtime by 74% through code profiling and analyzing individual components

### Autonomous Self-Balancing Robot

July 2019 - November 2019

- Extracted key objects in cluttered environments through image processing using OpenCV, allowing robot to autonomously navigate around a track
- Successfully enabled I2C and UART communication protocols between components by interfacing Raspberry Pi with camera, orientation sensor, and MSP430 micro-controller according to drawn schematics